# Time Transfer GPS Receiver MODEL: MR-600T

GPS receiver and antenna in a fully weather proof enclosure for time transfer application



- Quick start, 18 seconds warm start typical
- Low power consumption (0.9W typical)
- Wide supply voltages range (9~34VDC)

The AQTIME **MR-600T** is the integration of a timing GPS receiver and antenna in a compact/weather proof enclosure for time transfer application. It outputs UTC synchronized 1PPS with +/- 1 microseconds tolerance, which is close to an atomic clock in accuracy.

As a time transfer device, the AQTIME **MR-600T** is capable of operating with even 3(three) satellites after having a fix position with 3 or more satellites previously, so you can get precise time base anywhere on the Earth even under a very harsh environment where only one satellite is available.

## **Key Features :**

- UTC synchronized precise time base can be obtain anywhere on the earth at a relatively low cost
- Ultra compact, fully weather-proof, easy to mount
- Quick start, 18 seconds warm start typical
- Continue to output time data with even one satellite tracked
- Wide supply voltages range (9~34VDC)
- Low power consumption (0.9W typical)

## **Applications:**

- Time Stamp Data Logger
- Synchronization of radio base stations for cellular
- Phone, pagers,...etc.

Time control of computer terminals connected to network

### 1 PPS OUTPUT :

- Output signal level: RS232 (std), RS422(optional)
- Output data format: NMEA 0183
- Accuracy: +/- 1 u second (2DRMS) to UTC adjustment

#### Specifications: Navigation Inc.

https://www.bjnav.com/

| Specification Inc.           |               | https://www.binav.com/   |
|------------------------------|---------------|--|
| Specifications               | Parameter     | Description  |
| General                      |               | L1 frequency, C/A code(SPS),<br>12 Independent tracking channel (GPSP8633 & BBP1202) |
| Sonaitivity                  |               |  |
| Sensitivity                  |               | -143 dBm (tracking)  |
| Accuracy                     | Position      | 15m CEP , 5m(waas)   |
|                              | Velocity      | 0.1 m/sec. 0.05m/s(waas)   |
|                              | Time          | +/- 1 µs RMS (static mode)   |
| Acquisition                  | Cold start    | 70 sec. (typical)  |
|                              | Warm start    | 38 sec. (typical)  |
|                              | Hot start     | 8 sec. (typical)   |
| Reacquisition                |               | 100 ms typical (signal reacquisition)  |
|                              | Altitude      | 18000m max.  |
| Dynamics                     | Velocity      | 500 m/sec.   |
|                              | Vibration     | 4G max.  |
| <b>Operation Temperature</b> |               | -40°C to +85°C   |
| Storage Temperature          |               | -45°C to +90°C   |
| Operating Humidity           |               | 0% to 95% RH, non condensing   |
| Water Resistance             |               | 100% waterproof  |
| Primary Power                |               | 9V ~ 34V DC  |
| Power Consumption            |               | 130mA  |
| Protocol                     |               | NMEA-0183 v3.0 baud rate   |
|                              |               | 4800/9600/19200/38400/115200, default 4800   |
| Signal level                 |               | RS-232(standard),USB & RS-422 optional   |
| NMEA Message                 |               | GGA, GLL, GSA, GSV, RMC, and VTG   |
| EMI filter                   |               | Rejects power line interference  |
| Power cable                  |               | UL 2464 , 15M  |
| Enclosure                    |               | High impact, corrosion-proof polycarbonate resin                                     |
| Connector                    |               | open   |
| Dimensione                   | GPS Locator   | 112mm(Dia.) × 104 mm(H)  |
| Dimensions                   | Mounting Base |  |
| Weight                       |               | 270 grams  |
| Standard Mounting            |               | Concinnity and Solid design  |
| waterproof                   |               | IPX7   |

\* This specification is subject to change without prior notice

# User selectable datum \*Pole mount to 1"-14 UNS threaded mast

MR600T 1PPS Specification

- 1. The signal is generated after the MR-600T power on and continues until power down.
- 2. The rising edge of the signal is synchronized to the start of each GPS second.
- 3. The signal is valid after the initial position fix has been calculated.

4. The accuracy of the one-pulse-per-second output is maintained only while the MR600T can compute a valid position fix.

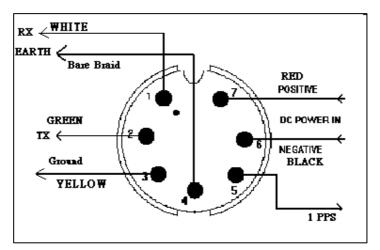
- 5. The default pulse width is 1u second.
- 6. The pulse height is 3V. BJTEK Navigation Inc.

7. EDEEXCENTAGet ion+Ind.usec with respect to the GPS second.

# **Power Interface RS232:**



| I/O PIN & CABLE |            |          |  |  |
|-----------------|------------|----------|--|--|
| Connector       | Wire       | Function |  |  |
| PIN1            | White      | Receive  |  |  |
| PIN2            | Green      | Transmit |  |  |
| PIN3            | Yellow     | Ground   |  |  |
| PIN4            | Bare Braid | Earth    |  |  |
| PIN5            | Blue       | 1 PPS    |  |  |
| PIN6            | Black      | Power-   |  |  |
| PIN7            | Red        | Power+   |  |  |



## **RS422 I/O Connection**

| Connector | Wire                | Function              |
|-----------|---------------------|-----------------------|
| PIN1      | White (R+)          | Differential input +  |
| PIN2      | Green (T+)          | Differential output + |
| PIN3      | Yellow (T-)         | Differential output - |
| PIN4      | To be detemined(R-) | Differential input -  |
| PIN5      | Blue                | 1PPS                  |
| PIN6      | Black ( - )         | Power-                |
| PIN7      | Red (+)             | Power+                |