

Marine GPS Locator

MODEL: MR-700B

Concinnity and Solid design for GPS Marine Locator
with Full Waterproof

Garmin compatible Marine GPS Receiver



MR-700B is Marine GPS receiver. Its excellent performance easily conquers the most difficult tasks. In addition , it provides various functions to meet customers' needs.**MR-700B** It provides marvelous navigation performance under dynamic conditions in areas with limited sky view like urban canyons.

Features

- 16 channel ANTARIS 4 positioning engine
- Ultra high sensitivity to -158 dBm
- Supports DGPS, WAAS, EGNOS and MSAS
- Supports Power saving modes
- 15 μ A backup current
- Ultra low power consumption 39mA

Possible Application:

- Marine Navigation.
- Fleet Management.
- Mileage Management.
- Tracking devices/system.
- Data logging for marine Navigation.
- Mapping devices for PC & Pocket PC.
- Marine Navigation or touring devices.
- AVL and Location-Based service system.

Specifications:

Specifications	Parameter	Description
General		L1 frequency, C/A code(SPS), 16 Independent tracking channel
Sensitivity		-158 dBm (tracking) -148dBm (Acquisition/Reacquisition)
Accuracy	Position	2.5 meters CEP / 2.0 meters CEP
	Time	50 nanosecond rms (1 PPS)
Acquisition	Cold start	45 sec. (typical)
	Warm start	33 sec. (typical)
	Hot start	3.5 sec. (typical)
Reacquisition		100 ms typical (signal reacquisition)
Dynamics	Altitude	18,000 meters (60,000 Feet) max
	Velocity	515 meters /sec (1000 Knots) max.
Operation Temperature		-40°C to +85°C
Storage Temperature		-45°C to +90°C
Operating Humidity		0% to 95% RH, non condensing
Water Resistance		100% waterproof
Primary Power		7V ~ 40V DC
Power Consumption		60mA
Protocol		NMEA, UBX (ublox proprietary), RTCM
Signal level		RS-232(standard), & RS-422 optional
NMEA Message		GGA, GLL, GSA, GSV, RMC, and VTG
DGPS Capability		Direct RTCM-SC104 interface
EMI filter		Rejects power line interference
Power cable		UL 2464/26Awg 10M
Enclosure		High impact, corrosion-proof polycarbonate resin
Connector		Open
Dimensions	GPS Locator	90.5mm(Dia.) × 108.5mm(H)
	Mounting Base	70mm(W) × 41.5mm(H) optional FB1 & FB2 & FB3
Weight		200 grams
Standard Mounting		Concinnity and Solid design

* This specification is subject to change without prior notice

User selectable datum *Pole mount to 1"-14 UNS threaded mast

RS232 I/O Connection

I/O PIN & CABLE	
Wire	Function
White (白)	Receive
Green(綠)	Transmit
Yellow(黃)	Ground or NG
Bare Braid(隔離地線/熱縮黑)	Earth/GND
Blue(藍)	1PPS
Purplr(紫)	Ground or NG
Black(黑)	Power-
Red(紅)	Power+

RS422 I/O Connection

Wire	Function
White (R+) 白	Differential input +
Green (T-) 綠	Differential output -
Yellow (T+) 黃	Differential output +
Purplr (R-) 紫	Differential input -
Blue 藍	1PPS
Bare Braid(隔離地線/熱縮黑)	Earth/GND
Black (-) 黑	Power-
Red (+) 紅	Power+

Output NMEA Messages

Table 3 NMEA-0183 V2.3 Output Messages

NMEA Sentence	Description
GGA (default)	Global Positioning System Fixed Data
GLL (default)	Geographic Position - Latitude/Longitude
GSA (default)	GNSS DOP and Active Satellites
GSV (default)	GNSS Satellites in View
RMC (default)	Recommended Minimum Specific GNSS data
VTG (default)	Course Over Ground and Ground Speed
ZDA (default)	Time and Date

GGA--- Global Positioning System Fixed Data

Table 4 contains the values for the following example:

\$GPGGA,092725.00,4717.11399,N,00833.91590,E,1,8,1.01,499.6,M,48.0,M,,0*5B

Table 4 GGA Data Format

Name	Example	Units	Description
Message ID	\$GPGGA		GGA protocol header
UTC Time	092725.00		hhmmss.ss, Current time
Latitude	4717.11399		ddmm.mmmmm, Degrees + minutes
N/S Indicator	N		N=north or S=south
Longitude	00833.91590		dddmm.mmmmm, Degrees + minutes
E/W Indicator	E		E=east or W=west
Position Fix Indicator	1		See Table 5
Satellites Used	8		Range 0 to 12
HDOP	1.01		Horizontal Dilution of Precision
MSL Altitude	499.6	m	
Units	M	meters	Meters (fixed field)
Geoid Separation	48.0	m	
Units	M	meters	Meters (fixed field)
Age of Differential Corrections		second	Blank (Null) fields when DGPS is not used
Diff. Ref. Station ID	0		
Checksum	*5B		
<CR> <LF>			End of message termination

Table 5 Position Fix Indicator

Value	Description
0	No fix or invalid
1	Standard GPS (2D/3D)
2	Differential GPS
6	Estimated (DR) Fix

GLL--- Geographic Position – Latitude/Longitude

Table 6 contains the values for the following example:

\$GPGLL,4717.11364,N,00833.91565,E,092321.00,A,A*60

Table 6 GLL Data Format

Name	Example	Units	Description
Message ID	\$GPGLL		GLL protocol header
Latitude	4717.11364		ddmm.mmmmm, Degrees + minutes
N/S Indicator	N		N=north or S=south
Longitude	00833.91565		dddmm.mmmmm, Degrees + minutes
E/W Indicator	E		E=east or W=west
UTC Time	092321.00		hhmmss.ss, Current time
Status	A		V = Data Invalid / Receiver Warning, A=Data Valid
Status	A		N=No Fix, A=Autonomous GNSS Fix, D=Differential GNSS Fix, E=Estimated/Dead Reckoning Fix
Checksum	*60		
<CR> <LF>			End of message termination

GSA---GNSS DOP and Active Satellites

Table 7 contains the values for the following example:

\$GPGSA,A,3,23,29,07,08,09,18,26,28,,,,,1.94,1.18,1.54*0D

Table 7 GSA Data Format

Name	Example	Units	Description
Message ID	\$GPGSA		GSA protocol header
Mode 1 (Smode)	A		See Table 8
Mode 2 (Fix Status)	3		See Table 9
Satellite Used	23		SV on Channel 1
Satellite Used	29		SV on Channel 2
			Repeated for each channel
Satellite Used			Sv on Channel 12
PDOP	1.94		Position Dilution of Precision (00.0 to 99.99)
HDOP	1.18		Horizontal Dilution of Precision (00.0 to 99.99)

VDOP	1.54		Vertical Dilution of Precision (00.0 to 99.99)
Checksum	*0D		
<CR> <LF>			End of message termination

Table 8 Mode 1 (Smode)

Value	Description
M	Manual- forced to operate in 2D or 3D mode
A	Automatic-allowed to automatically switch 2D/3D

Table 9 Mode 2 (Fix Status)

Value	Description
1	Fix not available
2	2D Fix
3	3D Fix

GSV---GNSS Satellites in View

Table 10 contains the values for the following example:

\$GPGSV,3,1,10,23,38,230,44,29,71,156,47,07,29,116,41,08,09,081,36*7F

\$GPGSV,3,2,10,10,07,189,,05,05,220,,09,34,274,42,18,25,309,44*72

\$GPGSV,3,3,10,26,82,187,47,28,43,056,46*77

Table 10 GSV Data Format

Name	Example	Units	Description
Message ID	\$GPGSV		GSV protocol header
Number of Messages	3		Total number of GPGSV messages being output , Range 1 to 3
Message Number	1		Number of this message, Range 1 to 3
Satellites in View	10		
Satellite ID	23		SV ID (GPS: 1-32, SBAS 33-64 (33=PRN120))
Elevation	38	degree	Maximum 90
Azimuth	230	degree	Range 0 to 359
SNR (C/No)	44	dBHz	Range 0 to 99, null when not tracking
			Data of 2nd, 3rd Satellite (same as above)
Satellite ID	29		SV ID
Elevation	71	degree	Maximum 90
Azimuth	156	degree	Range 0 to 359

SNR (C/No)	47	dBHz	Range 0 to 99, null when not tracking
Checksum	*7F		
<CR> <LF>			End of message termination

RMC---Recommended Minimum Specific GNSS Data

Table 11 contains the values for the following example:

```
$GPRMC,083559.00,A,4717.11437,N,00833.91522,E,0.004,77.52,091202,,,A*57
```

Table 11 RMC Data Format

Name	Example	Units	Description
Message ID	\$GPRMC		RMC protocol header
UTC Time	083559.00		hhmmss.ss, Current time
Status	A		A=data valid or V=data not valid
Latitude	4717.11437		ddmm.mmmmm, Degrees + minutes
N/S Indicator	N		N=north or S=south
Longitude	00833.91522		dddmm.mmmmm, Degrees + minutes
E/W Indicator	E		E=east or W=west
Speed	0.004	knots	Speed Over Ground
COG	77.52	degree	Course Over Ground (true)
Date	091202		Ddmmyy, Current Date in Day, Month Year format
Magnetic Variation		degrees	E=east or W=west (Not being output by receiver)
Magnetic variation E/W indicator			Not being output by receiver
Mode Indicator	A		N=No Fix, A=Autonomous GNSS Fix, D=Differential GNSS Fix, E=Estimated/Dead Reckoning Fix
Checksum	*53		
<CR> <LF>			End of message termination

VTG---Course Over Ground and Ground Speed

Table 12 contains the values for the following example:

```
$GPVTG,77.52,T,,M,0.004,N,0.008,K,A*06
```

Table 12 VTG Data Format

Name	Example	Units	Description
Message ID	\$GPVTG		VTG protocol header
COG	77.52	degrees	Course Over Ground (true)
	T		True
COG		degrees	Course Over Ground (maganetic) (Not being output by receiver)
	M		Magnetic
Speed	0.004	knots	Speed over ground
Units	N		Knots
Speed	0.008	km/hr	Speed over ground
Units	K		Kilometer per hour
Mode	A		N=No Fix, A=Autonomous GNSS Fix, D=Differential GNSS Fix, E=Estimated/Dead Reckoning Fix
Checksum	*0B		
<CR> <LF>			End of message termination

ZDA---Time and Date

Table 13 contains the values for the following example:

\$GPZDA,082710.00,16,09,2002,00,00*64

Table 13 ZDA Data Format

Name	Example	Units	Description
Message ID	\$GPZDA		ZDA protocol header
UTC Time	081727.00	degrees	hhmmss.ss
Day	16		01 to 31
Month	09		01 to 12
Year	2002		4 digit year
Local zone hours	00		(Not being output by receiver) (fixed to 00)
Local zone minutes	00		(Not being output by receiver) (fixed to 00)
Checksum	*64		
<CR> <LF>			End of message termination